### A Reaction Sphere for High Performance Attitude Control, Phase I

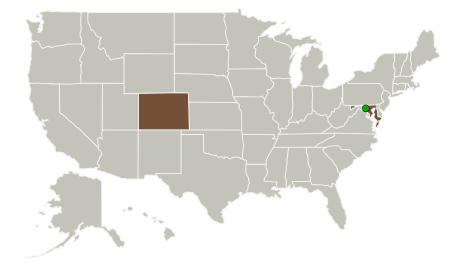


Completed Technology Project (2011 - 2011)

#### **Project Introduction**

Our innovative reaction sphere (Doty pending patent application serial number 61/164,868) has the potential to provide much higher performance than a conventional reaction wheel with substantially fewer resources. Using our proposed technology, a single reaction sphere can control three axes, substantially reducing mass, power, and cost when compared to a three wheel system. This device has no bearings: its spherical rotor is suspended within the stator by magnetic forces. Magnetic suspension reduces jitter, especially in a station-keeping mode where the torque and suspension forces can be reduced to a minimum. With clearances of  $\sim 1$  mm and no critical balance requirements, this device has very loose mechanical tolerances, further reducing cost. For initial development we propose a version suitable for control of a 1-3 kg Cubesat. At this scale, where spacecraft moments of inertia are very small, our low jitter torque, simplicity, and low cost are most advantageous. We also believe this approach is most likely to lead to an early flight opportunity.

#### **Primary U.S. Work Locations and Key Partners**





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#### Small Business Innovation Research/Small Business Tech Transfer

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Organizations Performing Work	Role	Туре	Location
NOQSI Aerospace, ltd	Lead Organization	Industry	Pine, Colorado
Goddard Space Flight Center(GSFC)	Supporting Organization	NASA Center	Greenbelt, Maryland

Primary U.S. Work Locations	
Colorado	Maryland

#### **Project Transitions**

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February 2011: Project Start



September 2011: Closed out

#### **Closeout Documentation:**

• Final Summary Chart(https://techport.nasa.gov/file/137921)

# Organizational Responsibility

# Responsible Mission Directorate:

Space Technology Mission Directorate (STMD)

#### **Lead Organization:**

NOQSI Aerospace, ltd

#### **Responsible Program:**

Small Business Innovation Research/Small Business Tech Transfer

## **Project Management**

#### **Program Director:**

Jason L Kessler

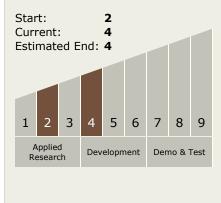
#### **Program Manager:**

Carlos Torrez

#### **Principal Investigator:**

John P Doty

# Technology Maturity (TRL)





Small Business Innovation Research/Small Business Tech Transfer

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# **Technology Areas**

#### **Primary:**

- TX17 Guidance, Navigation, and Control (GN&C)
  TX17.3 Control Technologies
  - ☐ TX17.3.4 Control Force/Torque Actuators

# **Target Destinations**

The Sun, Earth, The Moon, Mars, Others Inside the Solar System, Outside the Solar System

